Navtech GPS

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Quanta Micro

GNSS aided Inertial Navigation System

0.015° ROLL/PITCH 0.035° YAW



Outstanding Orientation & Navigation Performance, Disruptive SWaP-C





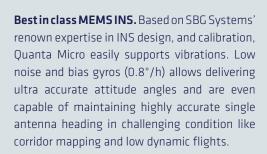












Reliability is key for robotics and autonomous applications. Quanta Micro has been designed from the ground-up to meet the most stringent requirements, delivering continuous navigation during GNSS outages, while featuring advanced interfacing capabilities in a tiny board level integration.



An optional secondary antenna maintains highly accurate heading in the lowest dynamic conditions!

Use anywhere: maximum performance

- Ideal for all UAV LiDAR mapping jobs
- Odometer and vehicle dynamic
- constraints in land applications
- 5 cm heave for marine applications

KEY FEATURES

- » Disruptive SWAP-C for a survey class INS
- Survey grade MEMS IMU maximizes performance and robustness
- » High bandwidth IMU for vibration resistance
- » Dual-frequency, quad-constellation GNSS, delivering cm accuracy
- » Fast & robust dual antenna heading
- » Smooth real time and post-processing Workflows with Qinertia Software
- » User friendly web interface
- » 8 GB embedded datalogguer
- » Full featured REST API for seamless OEM integration







1-sigma errors over full temperature range [-40 to 85°C]

INTERFACES

Aiding sensors	GNSS, RTCM, NTRIP, Odometer, DVL
Protocols	NMEA, ASCII, sbgECom (binary), REST API
Ethernet	Full duplex (10/100 base-T) PTP / NTP, NTRIP, Web interface, FTP
Datalogger	8 GB or 48 h @ 200 Hz
Serial ports	3x TTL UART, full duplex
CAN	1x CAN 2.0 A/B bus, up to 1 Mbps
Output rate	200Hz (IMU, INS)
1/0	4x: Inputs : PPS, Events in up to 1 kHz
	2x Outputs: SYNC out, PPS, Virtual odo
	LEDs drivers for status display
Connectors	44 pin contacts, 1.27 mm pitch, SMD
	2x U.FL for antennas

MECHANICAL & ENVIRONMENTAL

Dimensions	50 x 37 x 23 mm	
Weight	38 g	
Temperature range	-40 to 85°C	
Operating vibrations	8 g RMS (MIL-STD-810G)	
IMU Sensor range	490°/s 40g	
Operational limits	500 m/s 80 km altitude	
MTBF (computed)	50,000 h	

SYSTEM PERFORMANCE

Parameter	Single point	RTK	PPK
Roll/Pitch	0.03°	0.02°	0.015°
Heading Single ant.*	0.1°	0.08°	0.035°
Heading Dual ant. 2m	0.06°	0.06°	0.035°
Velocity	0.05 m/s	0.02 m/s	0.01 m/s
Position	1.2 m	0.01 m + 0.5ppm	0.01 m + 0.5ppm

^{*} Typical UAV mission, dependent on dynamics

GNSS

Features	SBAS, RTK, PPK
Signals	GPS: L1 C/A, L2C GLONASS: L10F, L20F GALILEO: E1, E5b BEIDOU: B1I, B2I
Update rate	PVT: 5 Hz, RAW 1 Hz
Time to first fix (cold start)	< 24 s

ELECTRICAL

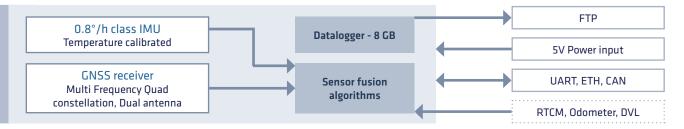
Power supply range	5.0V DC +/- 10%
Power consumption	1.1 W
Antenna Ports	5V DC – max 150 mA
	Gain: 17 - 50 dB

TIMING SPECIFICATIONS

Timestamp accuracy	< 200 ns
PTP accuracy	< 1 µs
PPS accuracy	< 10 μs (jitter < 10 μs)
Drift in dead reckoning	1 nnm

BLOCK DIAGRAM





Development Kit

Jump start your integration with the development kit allowing you to fully test Quanta Micro with USB, RJ45,DB9 connectors (Serial & CAN) and DIL connectors, allowing you to start the Software integration before your own system is available.





Qinertia post processing Software is a needed companion to get the maximum performances from Quanta Micro:

- » Forward + Backward processing
- » Tight coupling Inertial + GNSS
- » Remove uncertainty of RTK availability
- » Kinematic VBS, and much more...

Free Technical Support

Unlimited Firmware Updates

2-year Warranty

